

Cooperative capacity planning and resource allocation by mutual Outsourcing using ant algorithm in a decentralized supply chain

**Expert Systems with Applications (2009)
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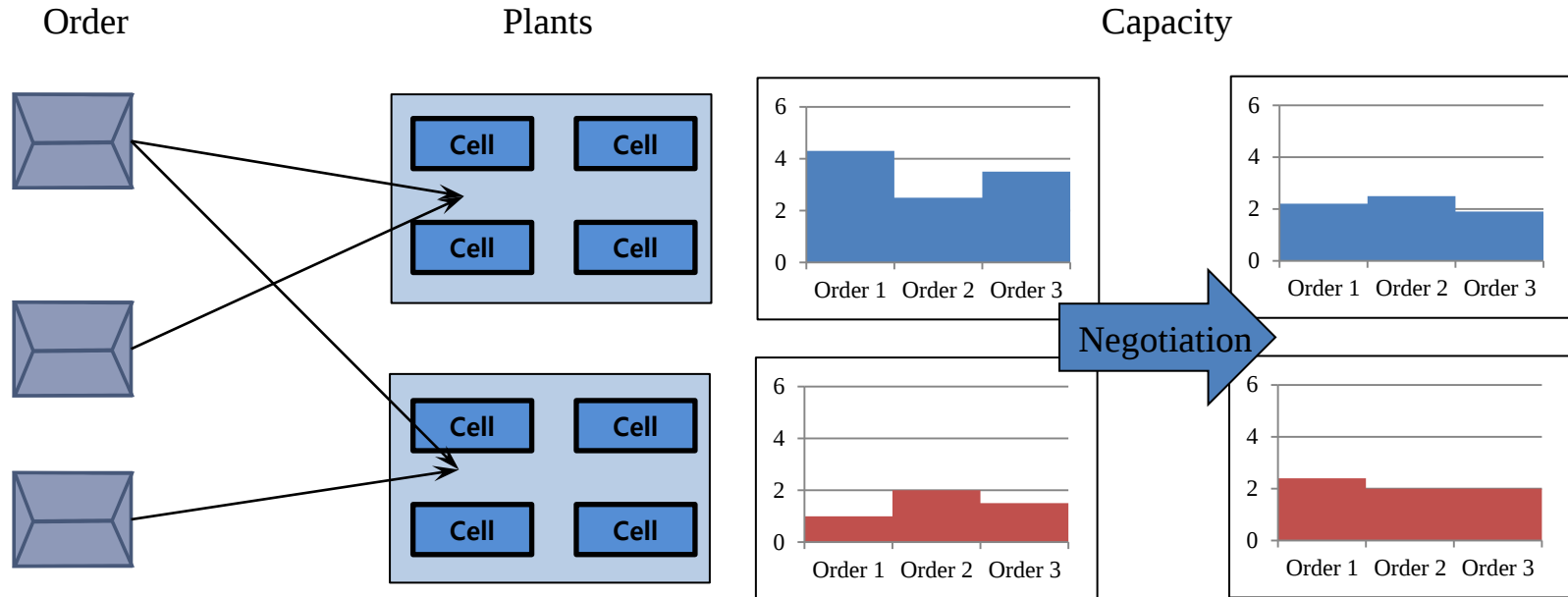


1 Introduction



Introduction

➤ Capacity planning and resource allocation with negotiation



The study focuses on

- Capacity planning with negotiation framework
- Allocating resources to fulfill all orders of products in each production period



Literature review

- Bard JF, Srinivasan K, Tirupati D.(1999)
 - Resource allocation + SA approach
- Tiwari MK, Vidyarth NK(2000)
 - Resource allocation + GA approach
- Wang K-J, Lin SH(2002)
 - Resource allocation + Capacity expansion + GA approach
- Wang K-J, Hou TC(2003)
 - Resource allocation + Capacity expansion + Multiple resource + Budget + GA approach
- S.M.Wang, J.C. Chena, K.-J.Wang(2007)
 - Resource allocation + Capacity expansion + Multiple resource + Budget + Inventory + GA approach



2 Problem description



Problem description

➤ **Problem**

- The cooperative capacity planning and resource allocation

➤ **Objective**

- Maximize the total profit

➤ **Decision variables**

- Capacity Planning Decision
- Resource Allocation Decision

➤ **Assumptions**

- the quality of product is not considered
- no backlogging



Problem description

➤ Parameters

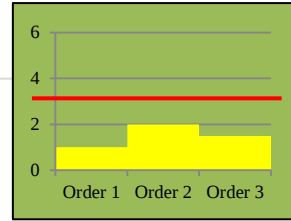
$a_{t,j}$	Configuration relationship between orders and manufacturing cells, $a_{tj} \in \{0,1\}$
$d_{k,j}$	Demand quantity (in pieces) of order j in planning period k , $k = \{1,2, \dots, p\}$
$\mu_{t,j}$	Throughput of manufacturing cell t when used to produce order j (in pieces per planning period)
W	Working hours of each period of time
$u_{k,t}$	Target utilization of manufacturing cell t in period k
$c_{k,t}$	Costs of purchasing manufacturing cell t in period k
I	Capital interest rate
C_t	Unit price of selling capacity of remaining manufacturing cells t of a capacity seller
$C_{t,j}$	Capacity seller's unit price of manufacturing cell t to produce capacity buyer's order j (or, equivalently, the unit cost of resource usage of the capacity buyer)
CC	upper bound of initial budget.
R	adjustable parameter of price of resource capacity.
P_j	unit profit of order j .

➤ Decision variables

$N_{k,t}$	number of manufacturing cell t in period k
$x_{k,t,j}$	quantity produced by manufacturing cell t to meet order j in period k .
$\delta_{k,t}$	increment (or decrement) number of manufacturing cell t from period $k-1$ to period k .
$N'_{k,t}$	number of remaining manufacturing cell t in period k .
$d'_{k,j}$	number of remaining quantities of order j in period k after task allocation of an individual factory is done.



Problem description



- Formulation – Individual factory capacity planning model
(a factory with capacity over demand) – demand need to be fulfill – Model 1

Object Function

$$\text{Max } z = \sum_{k=1}^p \frac{1}{(1+I)^k} \sum_{t=1}^v N_{k,t} C_t$$

(1) Obj. : Maximize Total profit

Subject to

$$\sum_{t=1}^v a_{tj} x_{ktj} = d_{kj}$$

(2) Capacity balancing equation

$$0 \leq \sum_{k=1}^p \sum_{t=1}^v \frac{c_{kt} \delta_{kt}}{(1+I)^k} \leq CC$$

(3) Upper bound of budget

$$N_{kt} - \sum_{j=1}^n \frac{a_{tj} x_{ktj}}{W u_{kt} \mu_{tj}} \geq 0$$

(4) Capacity limit of manufacturing cells

$$N_{kt} = N_{kt} - \sum_{j=1}^n \frac{a_{tj} x_{ktj}}{W u_{kt} \mu_{tj}}$$

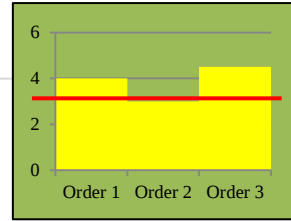
(5) Remanding capacity of manufacturing cells

$$\delta_{kt} = N_{kt} - N_{(k-1),t}$$

(6) The change in the number of machines



Problem description



- Formulation – Individual factory capacity planning model
(a factory with capacity over demand) – demand need not to be fulfill – Model 2

Object Function

$$\text{Max } z = \sum_{k=1}^p \sum_{t=1}^v \frac{\sum_{j=1}^n P_j x_{ktj} - c_{kt} \delta_{kt}}{(1+I)^k}$$

(1) Obj. : Maximize Total profit

Subject to

$$\sum_{t=1}^v a_{tj} x_{ktj} \leq d_{kj}$$

(2) Capacity balancing equation

$$0 \leq \sum_{k=1}^p \sum_{t=1}^v \frac{c_{kt} \delta_{kt}}{(1+I)^k} \leq CC$$

(3) Upper bound of budget

$$N_{kt} - \sum_{j=1}^n \frac{a_{tj} x_{ktj}}{W u_{kt} \mu_{tj}} \geq 0$$

(4) Capacity limit of manufacturing cells

$$\delta_{kt} = N_{kt} - N_{(k-1),t}$$

(5) The change in the number of machines

$$N_{kt}, x_{ktj} \in Z^+, \quad \delta_{kt} \in Z$$



Problem description

- Formulation – Inter-factories capacity planning model
(a factory with capacity over demand) – Model 3

Object Function

$$\text{Max} \quad z = \sum_{k=1}^p \sum_{t=1}^v \sum_{j=1}^n \frac{(P_j - C_{tj})x_{ktj}}{(1 + I)^k}$$

(1) Obj. : Maximize Total profit

Subject to

$$\sum_{t=1}^v a_{tj}x_{ktj} \leq d_{kj}$$

(2) Capacity balancing equation

$$N_{kt} - \sum_{j=1}^n \frac{a_{tj}x_{ktj}}{Wu_{kt}\mu_{tj}} \geq 0$$

(3) Capacity limit of manufacturing cells

$$N_{kt}, x_{ktj} \in Z^+$$



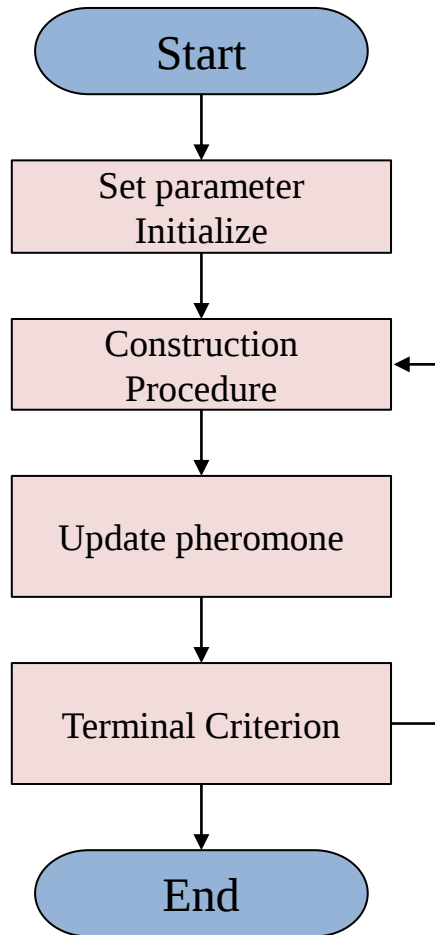
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Solution algorithms

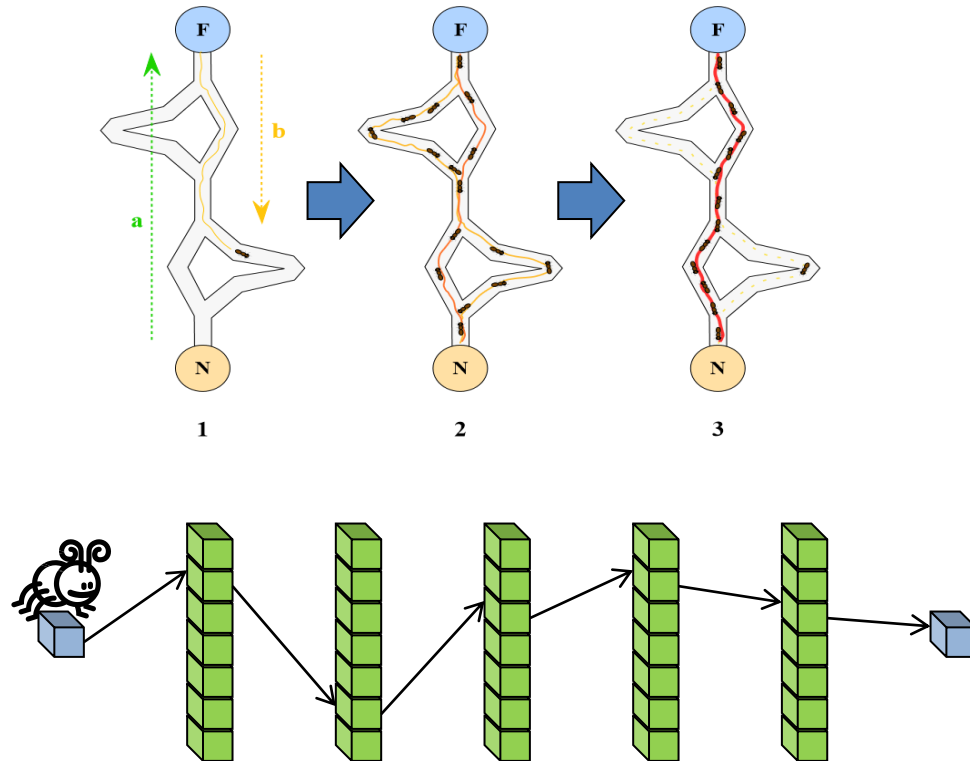


Solution algorithms

➤ Overall solution approach

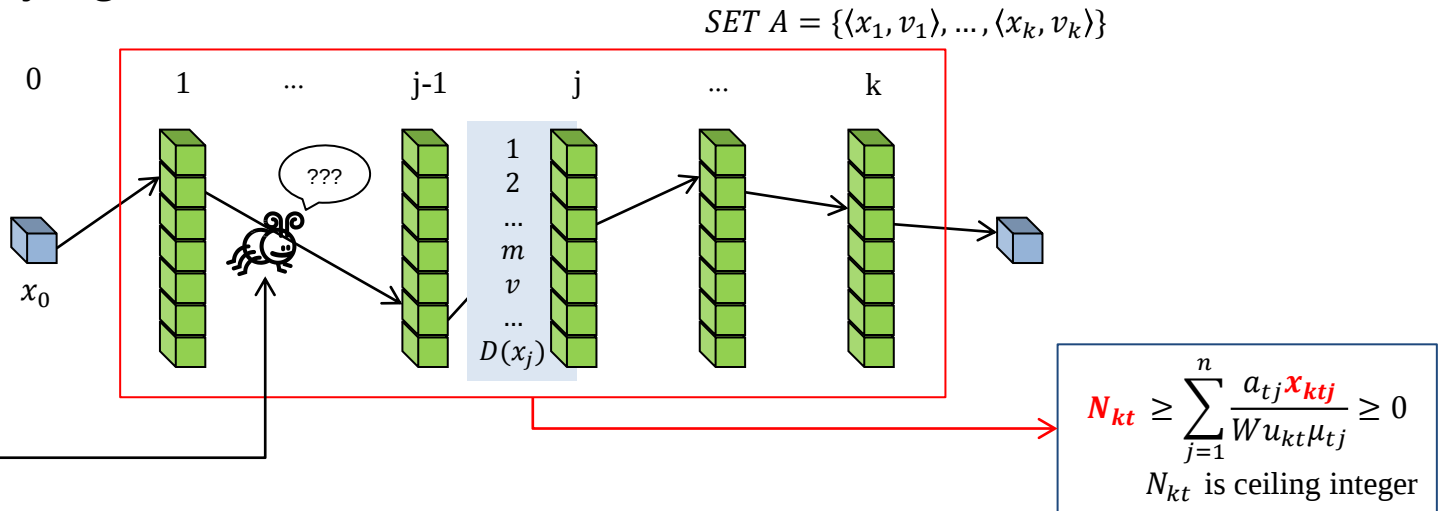


■ Concept of ant colony optimization algorithms



Solution algorithms

➤ Ant colony algorithm



Graph $G=(V,E)$

Amount of phomone = $\tau_A(\langle x_j, v \rangle) = \tau_{\langle x_{j-1}, m \rangle \in A}(\langle x_{j-1}, m \rangle, \langle x_j, v \rangle)$

Probability of transition = $p_A(\langle X_j, v \rangle) = \frac{[\tau_A(\langle X_j, v \rangle)]^\alpha [\eta_A(\langle X_j, v \rangle)]^\beta}{\sum_{w \in D(x_j)} [\tau_A(\langle X_j, w \rangle)]^\alpha [\eta_A(\langle X_j, w \rangle)]^\beta}$

Local

$$\tau(i, j) \leftarrow (1 - \rho) \cdot \tau(i, j) + \Delta\tau(A_k, i, j)$$

Global

$$\tau(i, j) \leftarrow (1 - \gamma) \cdot \tau(i, j) + \Delta\tau(A_l, i, j)$$

$$\exists!, [\eta_A(\langle X_j, v \rangle)]^\beta = \left(\frac{1}{D(x_j)}\right)^\beta$$

Initial solution $\beta=0$

Model 1 $\beta=0 \rightarrow \sum_{t=1}^v a_{tj} x_{ktj} = d_{kj}$

Model 2,3 $\beta=1 \rightarrow \sum_{t=1}^v a_{tj} x_{ktj} \leq d_{kj}$

$$\exists!, \Delta\tau(A_k, i, j) \begin{cases} = \frac{1}{TC(A_k)} & \text{if } \{i, j\} \in A_k \\ = 0 & \text{otherwise} \end{cases}$$



4 Experiments



Example and results

- Experiments environment
 - Computing power
P4 CPU / 256MB –Coding : JAVA

Parameters	Value
α (weighting the pheromone)	1
ρ (evaporation rate-local) γ (evaporation rate-global)	0.01
N_{ants} (number of artificial ant)	75
C (number of cycles in a trial)	1000
RF (number of reinforcement cycles)	25



Example and results

➤ Results

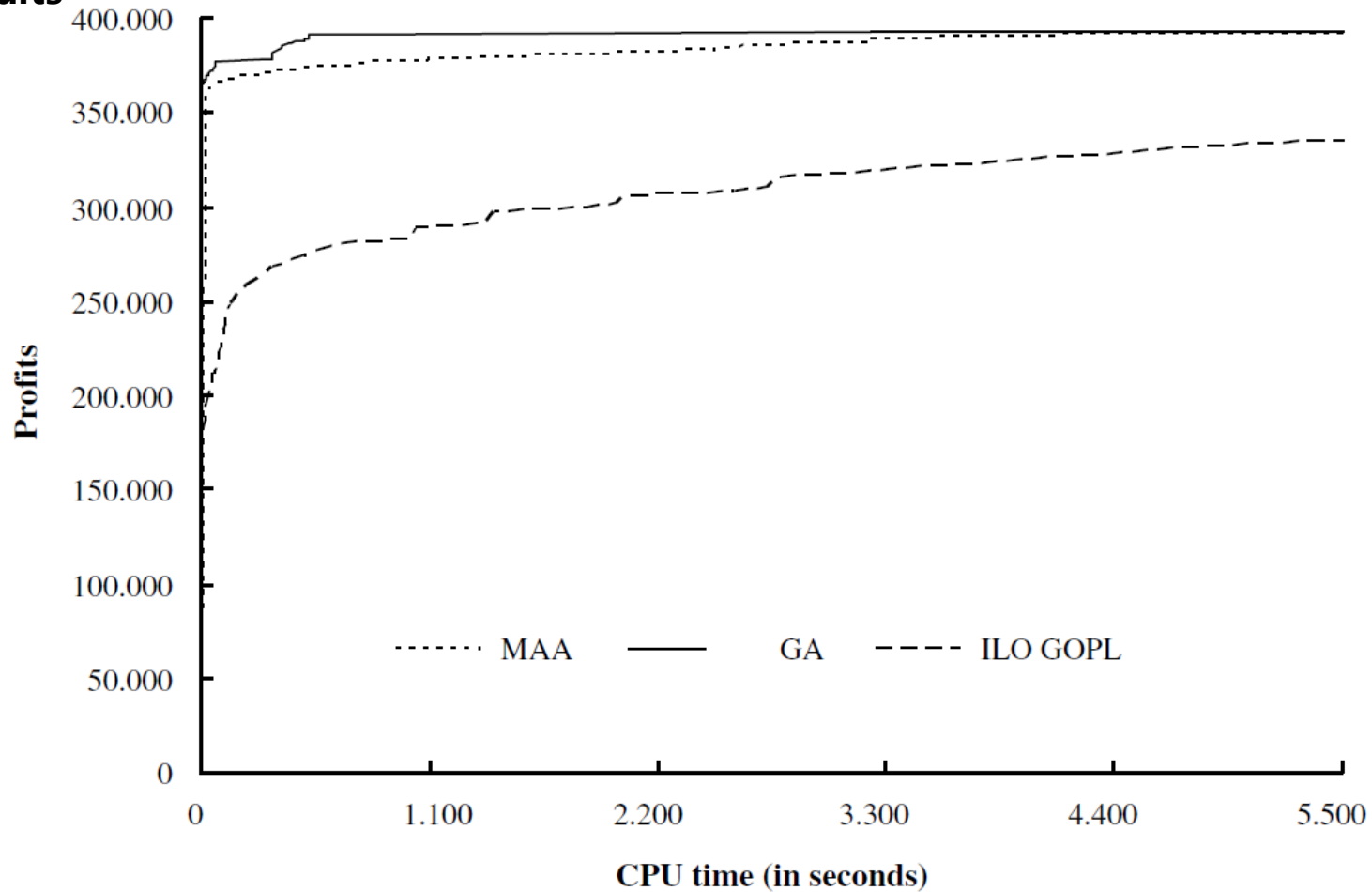


Fig. 6. Objective function evolutions of CPGA, MAA and ILOG OPL.



Example and results

➤ Results

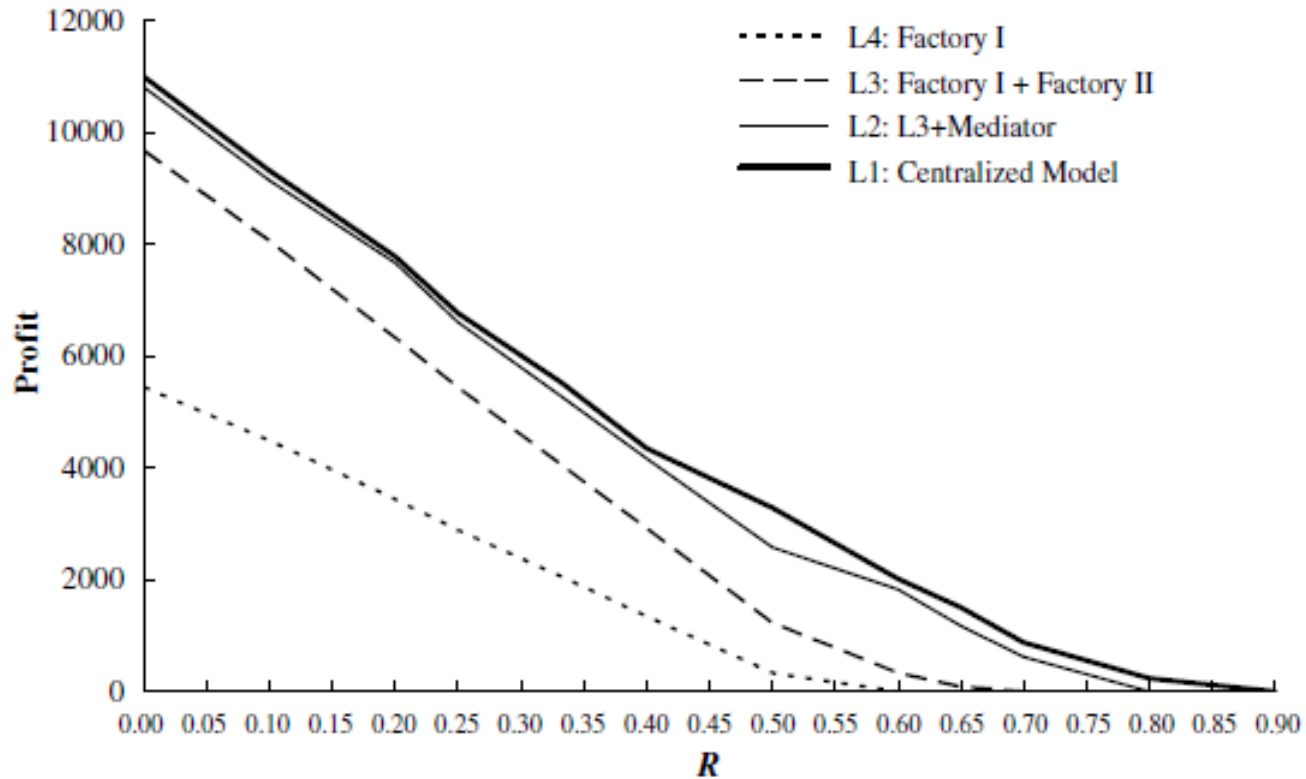


Fig. 7. Profit share structure for different R .



5 Conclusion



Conclusion

➤ **Conclusion**

- Presented a MILP Model
- Suggested ACO approach

